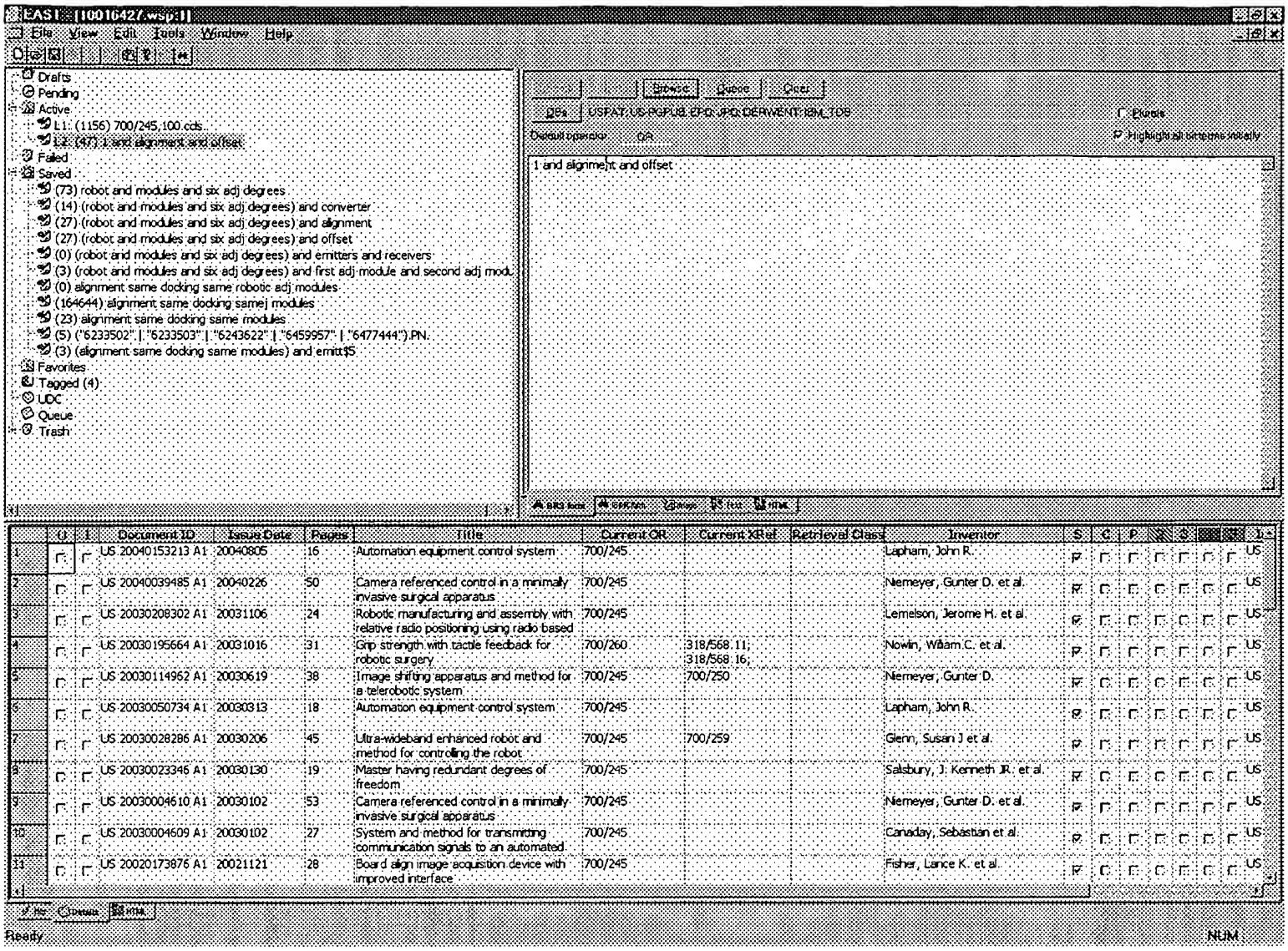

	U	I	Document ID	Issue Date	Pages	Title	Current OR	Current XRef	Retrieval Class	Inventor	S	C	P					
1			US 20040153213 A1	20040805	16	Automation equipment control system	700/245			Lapham, John R.								US
2			US 20040039485 A1	20040226	50	Camera referenced control in a minimally invasive surgical apparatus	700/245			Niemeyer, Gunter D. et al.								US
3			US 20030208302 A1	20031106	24	Robotic manufacturing and assembly with relative radio positioning using radio based	700/245			Lemelson, Jerome H. et al.								US
4			US 20030195664 A1	20031016	31	Grip strength with tactile feedback for robotic surgery	700/260	318/568.11; 318/568.16;		Nowlin, William C. et al.								US
5			US 20030114962 A1	20030619	38	Image shifting apparatus and method for a telerobotic system	700/245	700/250		Niemeyer, Gunter D.								US
6			US 20030050734 A1	20030313	18	Automation equipment control system	700/245			Lapham, John R.								US
7			US 20030028286 A1	20030206	45	Ultra-wideband enhanced robot and method for controlling the robot	700/245	700/259		Glenn, Susan J et al.								US
8			US 20030023346 A1	20030130	19	Master having redundant degrees of freedom	700/245			Salisbury, J. Kenneth JR. et al.								US
9			US 20030004610 A1	20030102	53	Camera referenced control in a minimally invasive surgical apparatus	700/245			Niemeyer, Gunter D. et al.								US
10			US 20030004609 A1	20030102	27	System and method for transmitting communication signals to an automated	700/245			Canaday, Sebastian et al.								US
11			US 20020173876 A1	20021121	28	Board align image acquisition device with improved interface	700/245			Fisher, Lance K. et al.								US